

8.4 Matrices

Matrix Multip.

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 4 & 7 & 10 \\ 5 & 8 & 11 \\ 6 & 9 & 12 \end{bmatrix} =$$

2×3 3×3
must match.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 5 \end{bmatrix}$$

3×2 3×2
Impossible

Dot products
of the rows of
the left matrix
with the cols of the
right matrix.

The result of the i th
row & j th column is
placed in the (i,j) entry
in the new matrix.

dot product of two vectors

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \Rightarrow (1)(4) + (2)(5) + (3)(6) \\ 4 + 10 + 18 \\ = 32$$

Ex:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 4 & 7 & 10 \\ 5 & 8 & 11 \\ 6 & 9 & 12 \end{bmatrix} = \begin{bmatrix} \circ & \circ & \circ \\ \circ & 12 & 16 \end{bmatrix}$$

2×3 3×3

2nd row x 3rd column

$$40 + 55 + 72 = 167$$

2nd row x 2nd column

$$28 + 40 + 54 = 122$$

Multiplicative Identity

$$I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Zero Matrix

$$U = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Associative

$$A(BC) = (AB)C$$

Distributive

$$A(B+C) = AB+AC$$

$$(B+C)A = BA+CA$$

Note: Commutative law does not work for matrices

$$\text{e.g. } AB \neq BA$$

Transpose

A^T = switch columns & rows.

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} \quad A^T = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}$$

Mult. Inverse

$$AB = BA = I$$

Non-singular \Rightarrow Inverse of A exists.

Singular Matrix - no inverse exists.

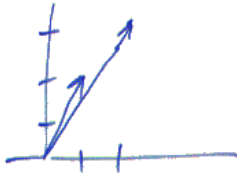
Derivative of a Matrix of Funct

$$\frac{dA}{dt} = \left(\frac{d a_{ij}}{dt} \right)_{m \times n}$$

Integration of a Matrix

$$\int_{t_0}^t A(s) ds = \left(\int_{t_0}^t a_{ij}(s) ds \right)_{m \times n}$$

Eigenvalues & Eigenvectors

$$x = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \Rightarrow \text{vector} \Rightarrow$$


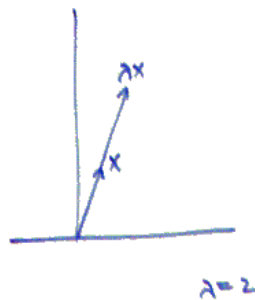
$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

This matrix stretched & changed the direction of x .

Let $A: n \times n$. λ is an eigenvalue and x is an eigenvector if

$$\underbrace{Ax}_{n \times 1} = \underbrace{\lambda x}_{\lambda \cdot n \times 1}$$



A does not change the direction of x , but does change the length of x by a factor of λ .

However, if λ is negative, the direction is completely opposite of x .

8.5 Matrices & Systems of Linear First Order Eq

$$X = \begin{pmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{pmatrix}$$

$$A = \begin{pmatrix} a_{11}(t) & a_{12}(t) & \dots & a_{1n}(t) \\ a_{21}(t) & a_{22}(t) & & \vdots \\ \vdots & & \ddots & \vdots \\ a_{n1}(t) & \dots & \dots & a_{nn}(t) \end{pmatrix}$$

$$F(t) = \begin{pmatrix} f_1(t) \\ f_2(t) \\ \vdots \\ f_n(t) \end{pmatrix}$$

The system

$$\begin{aligned} \frac{dx_1}{dt} &= a_{11}(t)x_1 + a_{12}(t)x_2 + \dots + a_{1n}(t)x_n + f_1(t) \\ \frac{dx_2}{dt} &= a_{21}(t)x_1 + a_{22}(t)x_2 + \dots + a_{2n}(t)x_n + f_2(t) \\ &\vdots \\ \frac{dx_n}{dt} &= a_{n1}(t)x_1 + a_{n2}(t)x_2 + \dots + a_{nn}(t)x_n + f_n(t) \end{aligned}$$

When the system is homogeneous, then $F(t) = 0$ and

$$X' = AX$$

\Rightarrow can write as

$$X' = AX + F$$

Ex:

$$\frac{dx}{dt} = -2x + 5y + e^t - 2t$$

$$\frac{dy}{dt} = 4x - 3y + 10t$$

$$\begin{bmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{bmatrix} = \begin{bmatrix} -2 & 5 \\ 4 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} e^t - 2t \\ 10t \end{bmatrix}$$

$$X' = A X + F$$

$$\rightarrow F = \begin{pmatrix} e^t - 2t \\ 10t \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t + \begin{pmatrix} -2 \\ 10 \end{pmatrix} t$$

DEF:

A solution vector on an interval I is any column vector

$$x = \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix} \text{ whose entries are}$$

differentiable functions satisfying the system $X' = AX + F$ on the interval

EX:

Verify that

$$X_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-2t} = \begin{pmatrix} e^{-2t} \\ -e^{-2t} \end{pmatrix} \text{ and}$$

$$X_2 = \begin{pmatrix} 3 \\ 5 \end{pmatrix} e^{6t} = \begin{pmatrix} 3e^{6t} \\ 5e^{6t} \end{pmatrix}$$

are solutions of $X' = \begin{pmatrix} 1 & 3 \\ 5 & 3 \end{pmatrix} X$

$$X_1' = \begin{pmatrix} -2e^{-2t} \\ 2e^{-2t} \end{pmatrix} \quad AX_1 = \begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-2t} = \begin{bmatrix} -2 \\ 2 \end{bmatrix} e^{-2t}$$

↑ they match! ↑

$$X_2' = \begin{pmatrix} 18e^{6t} \\ 30e^{6t} \end{pmatrix} \quad AX_2 = \begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} e^{6t} = \begin{bmatrix} 18 \\ 30 \end{bmatrix} e^{6t}$$

↑ they match! ↑

We're skipping the fundamental matrix in 8.5. We will return to it in sec 8.8.